

Developing USB device drivers on OS/2

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Agenda

OS/2 and USB

OS/2 USB Driver Stack

IDC interconnections

Device attachment

Class driver

HID Driver

Hostcontrollers on OS/2

UHCI

OHCI

EHCI (USB 2.0) not yett

Drivers from IBM

Printer

Keyboard / Mouse

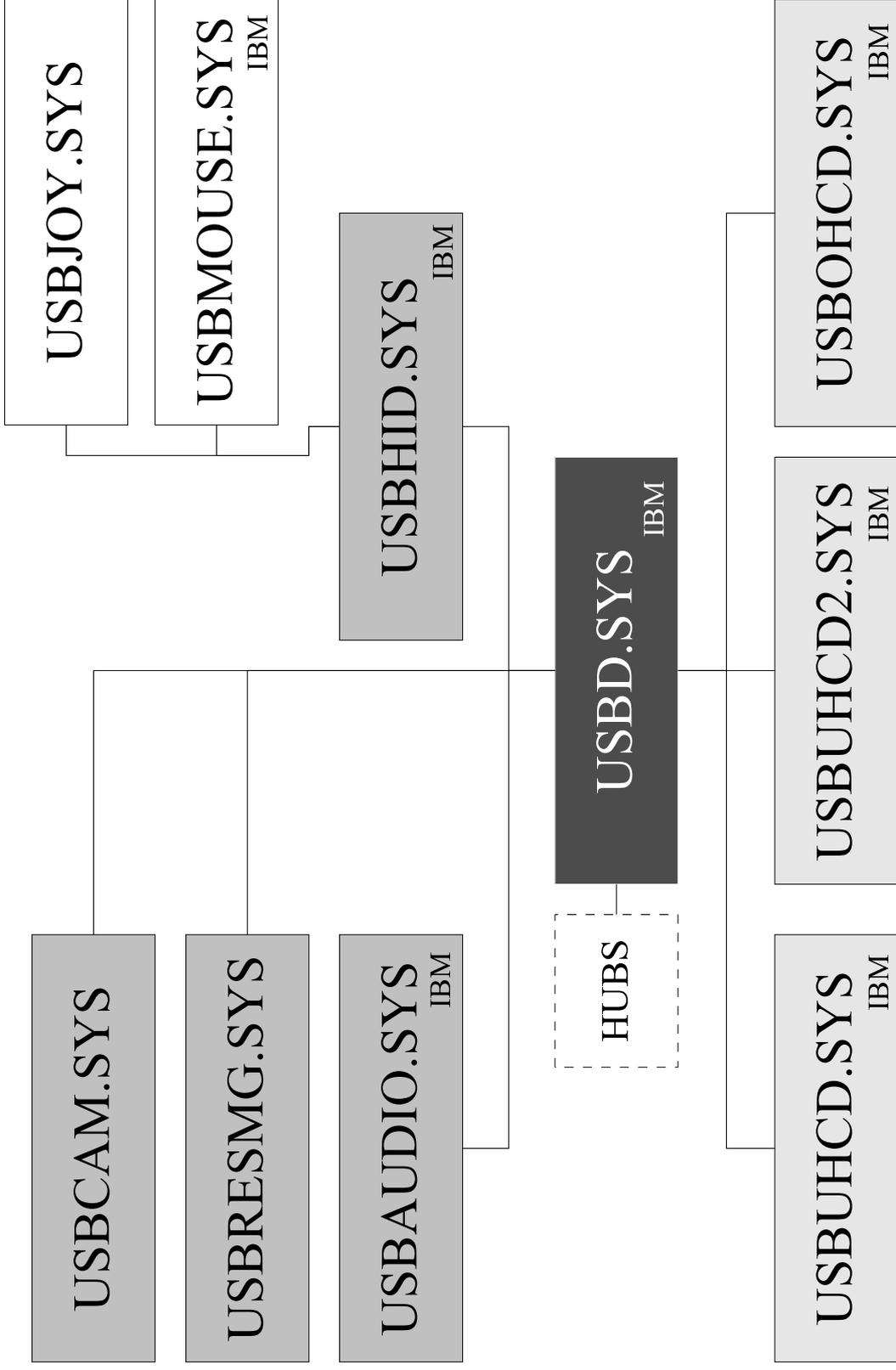
Audio

Modem

Mass Storage

Ethernet

OS/2 USB Driver Stack



IDC Interconnections

Attachment

To USBD during Init

To USBHID during InitComplete

IDC between USBD and Host Driver

IDC between USBD and Class Driver

IDC between UDBHID and HID Driver

IDC between USBD and Host Drv.

HCD → USBD

Category Host

Register HCD

Category USBD

Process IRQ

Clear Stalled Pipe

USB D → HCD

Category Host

Accept IO

Cancel IO

Reset Host

IDC between USB D and Class Drv.

USB D → Class

Category Class

Process IRQ

Check Service

Detach Device

Class → USB D

Category USB D

Register Class

Set Configuration

Set Interface

Accept IO

Cancel IO

IDC between UDBHID and HID drv.

USBHID → HID

Category Client

Check Service

Detach Device

Process IRQ

HID → USBHID

Category Class

Accept IO

Clear stalled dev.

Device Attachment

UHCI Detects a change in the port status

The virtual RootHub dev. in UHCI signals `HubStatusChanged` to **USB**D

USBD Gets the new hub status and the status of the ports of the hub

USBD Gets the `DeviceDescriptor`

USBD Gets the length of the `Configuration` (max. 512 Bytes)

USBD Gets the `Configuration`

USBD looks for driver for this device

Hub devices are handled by **USB**D itself

Enums all registered classdrivers and calls `IDC`

`USB_IDC_FUNCTION_CHKSERV` for non Hub devices

The IDC entry, heart of an USB driver

Receives USB_IDC_FUNCTION_CHKSERV

Receives USB_IDC_FUNCTION_DETDEV

Receives USB_IDC_FUNCTION_PRCIRQ

An IDC Sample function

```
void far IDCEntry (PRP_GENIOCTL PRP)
{
    USHORT status = PRP->rph.Status;
    PRP->rph.Status = 0;
    if (PRP->rph.Cmd != CMDGenIOCTL || !PRP->ParmPacket) {
        PRP->rph.Status |= STERR | USB_IDC_PARMERR;
    }
    else if (PRP->Category != USB_IDC_CATEGORY_CLASS) {
        PRP->rph.Status |= STERR | USB_IDC_WRONGCAT;
    }
    else
    {
        switch (PRP->Function)
        {
            case USB_IDC_FUNCTION_PRCIRQ: // 0x44
                PRP->rph.Status = status;
                IRQSwitch (PRP);
                break;
            case USB_IDC_FUNCTION_CHKSERV: // 0x45
                Service (PRP);
                break;
            case USB_IDC_FUNCTION_DETDEV: // 0x46
                Detach (PRP);
                break;
            default:
                PRP->rph.Status |= STERR | USB_IDC_WRONGFUNC;
        }
    }
    PRP->rph.Status |= STDON;
}
```

Checking for device Support

Class driver

- Check Vendor and Product ID
- Check Number of configurations
- Search for supported interface
- Check interface Needed Endpoints
- Set the Device Interface

HID device driver

- Check Usage (Page, Features ...)
- Get Report offsets
- Set Idle Time

Check Vendor/Product & configuration

```
void Service (PRP_GENIOCTL PRP_GENIOCTL)
{
    DeviceInfo FAR *pDevInfo;
    DeviceEndpoint FAR *pEndPointD;
    USBSetConf setConf;
    RP_GENIOCTL rp;
    USHORT VsrIndex, usInterface, usIFace;
    UCHAR ucEndp;

    pDevInfo = ((USBCDServe FAR *)pRP_GENIOCTL->ParmPacket)->pDeviceInfo;
    if (pDevInfo->bConfigurationValue)
    {
        // already configured
        PRP_GENIOCTL->rph.Status = USB_IDC_RC_SERVREJCTD;
        return;
    }
    if ( pDevInfo->descriptor.idVendor != VENDOR_HANDSPRING ||
        pDevInfo->descriptor.idProduct != PRODUCT_VISOR ||
        pDevInfo->descriptor.bcdDevice != DEVICE_RELEASE ||
        pDevInfo->descriptor.bNumConfigurations != 1)
    {
        PRP_GENIOCTL->rph.Status = USB_IDC_RC_SERVREJCTD;
        return;
    }
    ....
}
```

USB Device Info

```
typedef struct _DeviceInfo
{
    UCHAR          ctrlID;          // (00) controller ID
    UCHAR          deviceAddress;   // (01) USB device address
    UCHAR          bConfigurationValue; // (02) USB device configuration
                                   // value
    UCHAR          bInterfaceNumber; // (03) 0 based index in
                                   // interface array for this item
    UCHAR          lowSpeedDevice;  // (04) 0 for full speed device,
                                   // nonzero - low speed device
    UCHAR          portNum;         // (05) port number to which
                                   // device is attached
    USHORT         parentHubIndex;  // (06) index in hub table to
                                   // parent hub,
                                   // -1 for root hub device
    HDEVICE        rmDevHandle;     // (08) RM device handle
    SetupPacket    clearStalled;    // (12) setup packet for USB
                                   // internal use
    DeviceDescriptor descriptor;    // (20) Device descriptor
    UCHAR          configurationData[MAX_CONFIG_LENGTH]; // (38) device
                                   // configuration data
                                   // (1062)
} DeviceInfo;
```

USB Device Descriptor

```
typedef struct _device_descriptor_
{
    UCHAR    bLength;           // (00) Size of descriptor in bytes
    UCHAR    bDescriptorType;   // (01) 0x01 - DEVICE Descriptor type
    USHORT   bcdUSB;           // (02) USB Specification Release Number
    UCHAR    bDeviceClass;      // (04) Class Code
    UCHAR    bDeviceSubClass;   // (05) SubClass Code
    UCHAR    bDeviceProtocol;   // (06) Protocol Code
    UCHAR    bMaxPacketSize0;   // (07) Maximum packet size for endpoint 0
    USHORT   idVendor;          // (08) Vendor ID
    USHORT   idProduct;         // (10) Product ID
    USHORT   bcdDevice;         // (12) Device release number
    UCHAR    iManufacturer;     // (14) Index of string descriptor
                                   // describing manufacturer
    UCHAR    iProduct;          // (15) Index of string descriptor
                                   // describing product
    UCHAR    iSerialNumber;     // (16) Index of string descriptor
                                   // describing device's serial number
    UCHAR    bNumConfigurations; // (17) Number of possible configurations
                                   // (18)
} DeviceDescriptor;
```

Search for supported interface

```
...  
  
if (!(usIFace=SearchConfiguration( (PUCHAR) &pDevInfo->configurationData,  
    pDevInfo->descriptor.bNumConfigurations,  
    INTERFACE_CLASS_VENDOR,  
    INTERFACE_SUBCL_RESERVED,  
    INTERFACE_PROTOCOL_RESERVED)))  
{  
    PRP_GENIOCTL->rph.Status = USB_IDC_RC_SERVREJCTD;  
    return;  
}  
  
pDevInfo->bConfigurationValue = LOBYTE(usInterface);  
  
// Update global device list  
  
gVisors[VsrIndex].bConfValue = LOBYTE(usInterface);  
gVisors[VsrIndex].bInterface = HIBYTE(usInterface);  
  
....
```

Check for needed endpoints

```
...
for(ucEndp=1;ucEndp<=VISOR_NUM_BULKPIPES;ucEndp++) {
pEndPointD = GetEndPointDPtr ( pDevInfo->configurationData,
    pDevInfo->descriptor.bNumConfigurations, gVisors[VsrIndex].bConfValue,
    0, ucEndp | DEV_ENDPOINT_DIRIN);
if ( pEndPointD &&
    ((pEndPointD->bmAttributes & DEV_ENDPOINT_ATTRMASK) == DEV_ENDPOINT_BULK))
{
    gVisors[VsrIndex].bInEndpoint[ucEndp] = ucEndp | DEV_ENDPOINT_BULK;
    gVisors[VsrIndex].wMaxInSize[ucEndp] = pEndPointD->wMaxPacketSize;
}
else
{
    PRP_GENIOCTL->rph.Status = USB_IDC_RC_SERVREJCTD;
    return;
}
pEndPointD = GetEndPointDPtr ( pDevInfo->configurationData,
    pDevInfo->descriptor.bNumConfigurations, gVisors[VsrIndex].bConfValue,
    0, ucEndp | DEV_ENDPOINT_DIROUT);
if ( pEndPointD &&
    ((pEndPointD->bmAttributes & DEV_ENDPOINT_ATTRMASK) == DEV_ENDPOINT_BULK)) {
    gVisors[VsrIndex].bOutEndpoint[ucEndp] = ucEndp | DEV_ENDPOINT_DIROUT;
    gVisors[VsrIndex].wMaxOutSize[ucEndp] = pEndPointD->wMaxPacketSize;
}
else {
    PRP_GENIOCTL->rph.Status = USB_IDC_RC_SERVREJCTD;
    return;
}
}
...

```

Set device configuration

```
...
gVisors[VsrIndex].pDeviceInfo = pDevInfo;
gVisors[VsrIndex].active = TURNON;
gNoOfVisors++;

// Set Visor Configuration. The request and the request's parameters
// are sent to the device in the setup packet.
setConf.setConfiguration = &gVisor.setPack;
setConf.controllerId = pDevInfo->ctrlID;
setConf.deviceAddress = pDevInfo->deviceAddress;
setConf.classDriverDS = GetDS();
// desired configuration
setConf.configurationValue = gVisors[VsrIndex].bConfValue;
setConf.irqSwitchValue = VISOR_IRQ_SETCONF;
setConf.category = USB_IDC_CATEGORY_CLASS; // IRQ processor category
setmem ((PSZ)&rp, 0, sizeof(rp));
rp.rph.Cmd = CMDGenIOCTL;
rp.Category = USB_IDC_CATEGORY_USBD;
rp.Function = USB_IDC_FUNCTION_SETCONF;
rp.ParmPacket = (PVOID)&setConf;

USBCallIDC (gpUSBDIDC, gdsUSBDIDC, &rp);

pRP_GENIOCTL->rph.Status = USB_IDC_RC_OK;
}
```

USB I/O Request Block

```

typedef struct _USBRb {
    UCHAR   controllerId; // (00) controller ID
    UCHAR   deviceAddress; // (01) USB dev. address. Valid [1,127], 0 for unconfigured
    UCHAR   endPointId; // (02) device endpoint ID, valid [0,15]
    UCHAR   status; // (03) device status on request complete
    USHORT  flags; // (04) Low order byte sets transfer type,
                // High order byte gives packet details
    PCHAR   buffer1; // (06) Virtual address of data buffer
    USHORT  buffer1Length; // (10) Buffer length in bytes
    PCHAR   buffer2; // (12) Virtual address of second data buffer.
    USHORT  buffer2Length; // (16) Buffer length in bytes
    USHORT  serviceTime; // (18) Required service frequency in ms. Valid [0,255].
    USHORT  maxPacketSize; // (20) maximum packet size to be used for this endpoint
    PUSHORT usbIDC; // (22) Address of IRQ routine to be called for this request
    USHORT  usbDS; // (26) DS value for IRQ processing routine
    UCHAR   category; // (28) callers category (used in IRQ extension calls)
    ULONG   requestData1; // (29) data to be stored within request
    ULONG   requestData2; // (33) data to be stored within request
    ULONG   requestData3; // (37) data to be stored within request
    UCHAR   maxErrorCount; // (41) max. error count. Valid [0,3]. 0 - no error limit.
    struct _USBRb FAR *nextRb; // (42) far pointer to chained request block, not used
    UCHAR   altInterface; // (46) alt interface index support,
                // used when USBR_FLAGS_ALT_INTF is on
    // fields used for isohronous requests (USBR_FLAGS_DET_ISOHR is set in 'flags'
    UCHAR   isoFlags; // (47) isohronous request flags (opening call, regular call,
                // last call, cancel call, info call)
    USHORT  isoFrameLength; // (48) # of bytes to be sent in a frame (only opening call)
    USHORT  isoBuffers; // (50) max no of active buffers( only opening call)
                // (52)
} USBRb;

```

Setup Packet

```
typedef struct _setup_packet_{
    UCHAR    bmRequestType; // (00) Characteristics of request
    UCHAR    bRequest; // (01) Specific Request
    USHORT   wValue; // (02) Word-sized field
                // (value depends on request)
    USHORT   wIndex; // (04) typically Index or Offset
    USHORT   wLength; // (06) Number of bytes to Transfer
} SetupPacket;
```

D7: Data transfer direction

- 0 = Host-to-device
- 1 = Device-to-host

D6...5: Type

- 0 = Standard
- 1 = Class
- 2 = Vendor
- 3 = Reserved

D4...0: Recipient

- 0 = Device
- 1 = Interface
- 2 = Endpoint
- 3 = Other
- 4...31 = Reserved

- 0 GET_STATUS
- 1 CLEAR_FEATURE
- 2 Reserved for future use
- 3 SET_FEATURE
- 4 Reserved for future use
- 5 SET_ADDRESS
- 6 GET_DESCRIPTOR
- 7 SET_DESCRIPTOR
- 8 GET_CONFIGURATION
- 9 SET_CONFIGURATION
- 10 GET_INTERFACE
- 11 SET_INTERFACE
- 12 SYNCH_FRAME

HID Device attachment

```
void JOYserv (RP_GENIOCTL FAR *pRP_GENIOCTL)
{
    USHORT          index, joyIndex;
    USBHIDServe     FAR *pServData;
    ReportItemData FAR *pItem;
    USHORT          usOffset;
    // Check for free entry

    if (gNoOfJOYS < MAX_JOYS)
    {
        for (joyIndex = 0; joyIndex < MAX_JOYS; joyIndex++)
            if (!gJOY[joyIndex].active)
                break;
    }
    else
    {
        pRP_GENIOCTL->rph.Status = USB_IDC_RC_SERVREJCTD;
        return;
    }

    pServData = (USBHIDServe FAR *)pRP_GENIOCTL->ParmPacket;

    ...
}
```

USBHIDServe

```
typedef struct _USBHIDServe
{
    DeviceInfo FAR *pDeviceInfo; // far ptr to device data
    DeviceConfiguration FAR *devConf; // far ptr to device config. data
    ReportItemData FAR *itemData; // ptr to report item data array
    ItemUsage FAR *itemUsage; // ptr to extra usage data array
    ItemDesignator FAR *itemDesignator; // ptr to extra designator data array
    ItemString FAR *itemString; // ptr to extra string data array
    USHORT reportItemIndex; // starting report item index itemData
    USHORT versionFlags; // specific version flags (HID drafts)
} USBHIDServe;
```

Check Usage

```
...
index = pServData->reportItemIndex;
while (index != LAST_INDEX)
{
    pItem = pServData->itemData + index;

    if ( pItem->mainType == HID_REPORT_TAGS_MAIN_COLL &&
        pItem->itemFeatures.usagePage == HID_USAGE_PAGE_GDESKTOP &&
        pItem->localFeatures.usageMin == HID_GDESKTOP_USAGE_JOYSTICK &&
        pItem->localFeatures.usageMax == HID_GDESKTOP_USAGE_JOYSTICK )
    {
        break;
    }
    index = pItem->indexToNextItem;
}

if (index == LAST_INDEX)
{
    // no Joystick
    PRP_GENIOCTL->rph.Status = USB_IDC_RC_SERVREJCTD;
    return;
}
...
```

ReportItemData

```
typedef struct _RepItemData
{
    UCHAR        used;           // 00 nonzero if allocated
    UCHAR        interface;     // 01 interface index
    UCHAR        mainType;      // 02 item type - input, output,
                                // feature, collection
    USHORT       itemFlags;     // 03 item flags
    USHORT       parColIndex;   // 05 parent collection index
                                // (LAST_INDEX - no parent collection)
    USHORT       indexToNextItem; // 07 index to next main item for this
                                // report
    // item features
    ItemFeatures itemFeatures;  // 09

    // item local data
    LocalFeatures localFeatures; // 41
                                // 59
} ReportItemData;
```

ItemFeatures

```
typedef struct _item_features
{
    UCHAR    reportID;        // 09 report ID item belongs to
    ULONG    reportSize;     // 10 data size for this item
    ULONG    reportCount;    // 14 element count for current item
    USHORT   usagePage;     // 18 item's usage page
    LONG     logMin;         // 20 logical minimum for this item
    LONG     logMax;         // 24 logical maximum for this item
    LONG     phyMin;         // 28 physical value minimum
    LONG     phyMax;         // 32 physical value maximum
    ULONG    unit;          // 36 units of measurement
    UCHAR    unitExponent   // 40 exponent value
                        // 41
} ItemFeatures;
```

LocalFeatures

```
typedef struct _local_features
{
    // usage information
    USHORT      usagePage;           // 41 local (only this item) usage page
    USHORT      usageMin;           // 43 usage minimum
    USHORT      usageMax;           // 45 usage maximum
    USHORT      indexToUsageList; // 47
    // physical data references
    USHORT      designatorMin;      // 49
    USHORT      designatorMax;      // 51
    USHORT      indexToDesignator; // 53
    // string data references
    UCHAR       stringMin;          // 55
    UCHAR       stringMax;          // 56
    USHORT      indexToStrings;     // 57
} LocalFeatures; // 59
```

Check length of report

```
...
// Check if the total report Length of the device can be handled
gJOY[joyIndex].ReportLength = 0;
index = pServData->reportItemIndex;

while (index != LAST_INDEX)
{
    pItem = pServData->itemData + index;
    gJOY[joyIndex].ReportLength += pItem->itemFeatures.reportSize*
        pItem->itemFeatures.reportCount;
    index = pItem->indexToNextItem;
}

gJOY[joyIndex].ReportLength= (gJOY[joyIndex].ReportLength+BITS_IN_BYTE-1)
/BITS_IN_BYTE;

if (gJOY[joyIndex].ReportLength > sizeof(gJOY[joyIndex].buffer))
{
    // Report is to long
    PRP_GENIOCTL->rph.Status = USB_IDC_RC_SERVREJCTD;
    return;
}
...
```

Parse for needed reports

```
...
index = pServData->reportItemIndex;
usOffSet = 0;
gJOY[joyIndex].ulCapsAxes = 0;
gJOY[joyIndex].ulCapsSliders = 0;
setmem((PSZ)&gJOY[joyIndex].DevCapsJoy,0,sizeof(DEVCAPS));
setmem((PSZ)&gJOY[joyIndex].joyState,0,sizeof(JOYSTATE));
setmem((PSZ)&gJOY[joyIndex].AxeUnits,0,sizeof(JOYAXEUNIT)*JOYMAX_AXES);
setmem((PSZ)&gJOY[joyIndex].Items,FULL_BYTE,sizeof(JOYITEM)*JOYMAXITEMS);
while (index != LAST_INDEX) {
    pItem = pServData->itemData + index;

    if ( pItem->mainType == HID_REPORT_TAGS_MAIN_INPUT &&
        pItem->itemFeatures.usagePage == HID_USAGE_PAGE_GDESKTOP) {
        if ( pItem->localFeatures.usageMin >= HID_GDESKTOP_USAGE_X &&
            pItem->localFeatures.usageMax <= HID_GDESKTOP_USAGE_Z ) {
            usOffSet = SetupXYZAxes(joyIndex, pItem, usOffSet);
            gJOY[joyIndex].inInterface = pItem->interface;
        }
        else
        { ... }
    }
    else
    { ... }
    index = pItem->indexToNextItem;
}
...
```

Last Check and SetIdleTime

```
if ( (ULONG)0==gJOY[joyIndex].DevCapsJoy.ulButtons ||
      (ULONG)0==gJOY[joyIndex].DevCapsJoy.ulAxes) {
    // No Axes or No buttons
    PRP_GENIOCTL->rph.Status = USB_IDC_RC_SERVREJCTD;
    return;
}
gJOY[joyIndex].joyAddr = pServData->pDeviceInfo->deviceAddress;
gJOY[joyIndex].controllerID = pServData->pDeviceInfo->ctrlID;
gJOY[joyIndex].interruptPipeAddress =
GetInterruptPipeAddr( pServData->pDeviceInfo->configurationData,
                      pServData->pDeviceInfo->descriptor.bNumConfigurations,
                      pServData->pDeviceInfo->bConfigurationValue,
                      gJOY[joyIndex].inInterface);
gJOY[joyIndex].setITpack.bmRequestType = REQTYPE_TYPE_CLASS |
                                      REQTYPE_RECIPIENT_INTERFACE;
gJOY[joyIndex].setITpack.bRequest = HID_REQUEST_SET_IDLE;
gJOY[joyIndex].setITpack.wValue = 0x0000; // all reports only if changed
gJOY[joyIndex].setITpack.wIndex = gJOY[joyIndex].inInterface;
gJOY[joyIndex].setITpack.wLength = NULL;
gJOY[joyIndex].active = TURNON;
gNoOfJOYS++;

SetIdleTime (joyIndex, JOY_IRQ_STATUS_IDLESET);

PRP_GENIOCTL->rph.Status = USB_IDC_RC_OK;
}
```

SetIdleTime

```
void SetIdleTime (USHORT joyIndex, USHORT kbdIRQstatus) {
    USBRB    rbHID; // I/O request block
    RP_GENIOCTL rpHID; // request packet

    rbHID.buffer1 = (PUCCHAR)&gJOY[joyIndex].setITpack;
    rbHID.buffer1Length = sizeof(gJOY[joyIndex].setITpack);
    rbHID.buffer2 = NULL;
    rbHID.buffer2Length = NULL;
    rbHID.controllerId = gJOY[joyIndex].controllerID;
    rbHID.deviceAddress = gJOY[joyIndex].joyAddr;
    rbHID.endpointId = USB_DEFAULT_CTRL_ENDPT;
    rbHID.status = 0; // not used
    rbHID.flags = USBR_FLAGS_TTYPE_SETUP;
    rbHID.serviceTime = USB_DEFAULT_SRV_INTV;
    rbHID.maxPacketSize = USB_DEFAULT_PKT_SIZE;
    rbHID.maxErrorCount = USB_MAX_ERROR_COUNT;
    rbHID.usbIDC = (PUSBIDEntry)JOYidc; // Address of IRQ processor function
    rbHID.usbDS = GetDS();
    rbHID.category = USB_IDC_CATEGORY_CLIENT; // set client layer as IRQ processor
    rbHID.requestData1 = JOY_IRQ_STATUS_IDLESET; // MAKEULONG (kbdIRQstatus, 0);
    rbHID.requestData2 = MAKEULONG (joyIndex, 0);
    rbHID.requestData3 = 0; // not used
    setmem((PSZ)&rpHID, 0, sizeof(rpHID));
    rpHID.rph.Cmd = CMDGenIOCTL;
    rpHID.Category = USB_IDC_CATEGORY_CLASS;
    rpHID.Function = USB_IDC_FUNCTION_ACCIO;
    rpHID.ParmPacket = (PVOID)&rbHID;

    USBCallIDC (gpHIDIDC, gdsHIDIDC, (RP_GENIOCTL FAR *)&rpHID);
}
}
```

Get Report Position

```
USHORT SetupPOVs(USHORT joyIndex, ReportItemData FAR *pItem, USHORT usOffset)
{
    USHORT usCount;
    usCount = 0;
    while( usCount < (USHORT)pItem->itemFeatures.reportCount &&
           gJOY[joyIndex].DevCapsJoy.ulPOVs < MAX_POVS)
    {
        gJOY[joyIndex].Items[JOYOFS_POV0+usCount].bReport = pItem->itemFeatures.reportID;
        gJOY[joyIndex].Items[JOYOFS_POV0+usCount].usOffse = usOffset;
        gJOY[joyIndex].Items[JOYOFS_POV0+usCount].usReportSize =
            (USHORT)pItem->itemFeatures.reportSize;
        gJOY[joyIndex].AxeUnits[JOYOFS_POV0+usCount].logMin = pItem->itemFeatures.logMin;
        gJOY[joyIndex].AxeUnits[JOYOFS_POV0+usCount].logMax = pItem->itemFeatures.logMax;
        gJOY[joyIndex].AxeUnits[JOYOFS_POV0+usCount].phyMin = pItem->itemFeatures.phyMin;
        gJOY[joyIndex].AxeUnits[JOYOFS_POV0+usCount].phyMax = pItem->itemFeatures.phyMax;
        gJOY[joyIndex].AxeUnits[JOYOFS_POV0+usCount].unit = pItem->itemFeatures.unit;
        gJOY[joyIndex].AxeUnits[JOYOFS_POV0+usCount].unitExponent =
            pItem->itemFeatures.unitExponent;

        gJOY[joyIndex].DevCapsJoy.ulPOVs++;
        usOffset += pItem->itemFeatures.reportSize;
        usCount++;
    }
    // Just in case the device has more than MAX_POVS Hatswitches
    usOffset += pItem->itemFeatures.reportSize *
        (pItem->itemFeatures.reportCount- usCount);

    return usOffset;
}
```

Parse Report

```
void InterruptDataReceived (RP_GENIOCTL FAR *pRP_GENIOCTL)
{
    USBRB FAR *processedRB;
    BYTE *pIntData;
    USHORT joyIndex, i;
    LONG lValue;
    processedRB = (USBRB FAR *)pRP_GENIOCTL->ParmPacket;
    joyIndex = LOUSHORT (processedRB->requestData2);

    if (gDevice)
        if (joyIndex != gJoyIndex)
            return;

    pIntData = (BYTE *)&gJOY[joyIndex].buffer;

    setmem((PSZ)&gJOY[joyIndex].joyState, 0, sizeof(JOYSTATE));
}
```

Parse Report cont.

```
...
i=0;
while(i< (USHORT)gJOY[joyIndex].DevCapsJoy.ulPOVs)
{
    lValue = GetLogValue(joyIndex, JOYDFS_POV0+i);
    if(lValue)
    {
        if( gJOY[joyIndex].AxeUnits[JOYDFS_POV0+i].unit)
        {
            // Assume degrees and log 1 as top which is 0°
            lValue = (lValue -1)*
                (gJOY[joyIndex].AxeUnits[JOYDFS_POV0+i].phyMax-
                 gJOY[joyIndex].AxeUnits[JOYDFS_POV0+i].phyMin)/
                (gJOY[joyIndex].AxeUnits[JOYDFS_POV0+i].logMax-
                 gJOY[joyIndex].AxeUnits[JOYDFS_POV0+i].logMin);
            // Report in hundredths of degrees
            if( gJOY[joyIndex].AxeUnits[JOYDFS_POV0+i].phyMax>=270 &&
                gJOY[joyIndex].AxeUnits[JOYDFS_POV0+i].phyMax<=360)
                lValue *=100;
        }
        else
        {
            // No Units so no physical values translate to degrees
            lValue = (lValue-1) * (36000/gJOY[joyIndex].AxeUnits[JOYDFS_POV0+i].logMax);
        }
    }
    else
    {
        lValue = 0x0000FFFF; // centered
    }
    gJOY[joyIndex].joyState.rgdwPOV[i] = lValue;
    i++;
}
...
```

Item Usage, Designator and String

```
typedef struct _item_usage
{
    UCHAR          used;                // nonzero if allocated
    USHORT         indexToNextUsageData;
    USHORT         usagePage;          // local (only this item) usage page
    USHORT         usageMin;           // usage minimum
    USHORT         usageMax;           // usage maximum
} ItemUsage;

typedef struct _item_designator
{
    UCHAR          used;                // nonzero if allocated
    USHORT         indexToNextDesignatorData;
    USHORT         designatorMin;      // designator minimum
    USHORT         designatorMax;      // designator maximum
} ItemDesignator;

typedef struct _item_strings
{
    UCHAR          used;                // nonzero if allocated
    USHORT         indexToNextStringData;
    UCHAR          stringMin;          // string minimum
    UCHAR          stringMax;          // string maximum
} ItemString;
```

The Brain, the IRQ function

Gets called from the IDC function to process
USB_IDC_FUNCTION_PRCIRQ

Each call to a USBCallIDC is followed by an
IRQ which gets processed in it

Sample IRQ function

```
void JOYirq (RP_GENIOCTL FAR *pRP_GENIOCTL)
{
    USBRB FAR *processedRB;
    UCHAR oldCat;

    processedRB = (USBRB FAR *)pRP_GENIOCTL->ParmPacket;

    if (pRP_GENIOCTL->rph.Status != USB_IDC_RC_OK)
    {
        if (processedRB->status & USRB_STATUS_STALLED)
        {
            if ( processedRB->requestData1!=JOY_IRQ_STATUS_STALLED )
            {
                oldCat=pRP_GENIOCTL->Category;
                JOYclearStalled(pRP_GENIOCTL);
                pRP_GENIOCTL->Category=oldCat;
            }
            return;
        }
        return;
    }
    ...
}
```

IRQ function cont.

```
...
switch (processedRB->requestData1)
{
  case JOY_IRQ_STATUS_IDLESET:
    PRP_GENIOCTL->rph.Status=STATUS_DONE; //always ok
    ReadInterruptPipe (pRP_GENIOCTL);
    break;
  case JOY_IRQ_STATUS_DURATION:
    break;
  case JOY_IRQ_STATUS_INTPIPE:
    InterruptDataReceived (pRP_GENIOCTL);
    ReadInterruptPipe (pRP_GENIOCTL);
    break;
  case JOY_IRQ_STATUS_SETACK:
    break;
  case JOY_IRQ_STATUS_STALLED:
    ReadInterruptPipe (pRP_GENIOCTL);
    break;
  default:;
}
}
```

ReadInterruptPipe

```

void ReadInterruptPipe (PRP_GENIOCTL PRP_GENIOCTL) {
    USBRB FAR *processedRB;
    USBRB      hcdReqBlock;
    RP_GENIOCTL rp_USBReq;
    USHORT     deviceIndex;

    processedRB = (USB RB FAR *)PRP_GENIOCTL->ParmPacket;
    deviceIndex = LOUSHORT(processedRB->requestData2);
    setmem((PSZ)gJOY[deviceIndex].buffer, UI_RESERV, sizeof(gJOY[deviceIndex].buffer));
    hcdReqBlock.controllerId = processedRB->controllerId;
    hcdReqBlock.deviceAddress = processedRB->deviceAddress; // use default address
    hcdReqBlock.endPointId = gJOY[deviceIndex].interruptPipeAddress;
    hcdReqBlock.status = 0; // not used
    hcdReqBlock.flags = USBR_FLAGS_TTYPE IN | USBR_FLAGS_DET_INTRPT;
    if (!(processedRB->flags & USBR_FLAGS_DET_DTGGLEON))
        hcdReqBlock.flags |= USBR_FLAGS_DET_DTGGLEON;
    hcdReqBlock.buffer1 = (PUCHAR)gJOY[deviceIndex].buffer;
    hcdReqBlock.bufferLength = gJOY[deviceIndex].ReportLength; // no additional data to be sent to/from host
    hcdReqBlock.buffer2 = NULL; // to complete this request
    hcdReqBlock.buffer2Length = 0;
    hcdReqBlock.serviceTime = USB_DEFAULT_SRV_INTV;
    hcdReqBlock.maxPacketSize = USB_DEFAULT_PKT_SIZE;
    hcdReqBlock.maxErrorCount = USB_MAX_ERROR_COUNT;
    hcdReqBlock.usbIDC = (PUSBIDEntry)JOYidc; // Address of IRQ proc.
    hcdReqBlock.usbDS = GetDS();
    hcdReqBlock.category = USB_IDC_CATEGORY_CLIENT; // set USBD layer as IRQ processor
    hcdReqBlock.requestData1 = JOY_IRQ_STATUS_INTPIPE;
    hcdReqBlock.requestData2 = MAKEULONG(deviceIndex, 0); // index in device table
    hcdReqBlock.requestData3 = 0; // not used
    setmem((PSZ)&rp_USBReq, 0, sizeof(rp_USBReq));
    rp_USBReq.rph.Cmd = CMDGenIOCTL;
    rp_USBReq.Category = USB_IDC_CATEGORY_CLASS;
    rp_USBReq.Function = USB_IDC_FUNCTION_ACCIO;
    rp_USBReq.ParmPacket = (PVOID)&hcdReqBlock;

    USBCallIDC (gPHIDIDC, gdsHIDIDC, (RP_GENIOCTL FAR *)&rp_USBReq);
}

```

GetLogValue

```
LONG GetLogValue( USHORT joyIndex, USHORT ItemOfs)
{
    LONG rc = 0;
    USHORT usOffset, usByteOfs, StartBit, usSize;
    BYTE *pIntData, bRem;
    usOffset = gJOY[joyIndex].Items[ItemOfs].usOffset;
    usSize = gJOY[joyIndex].Items[ItemOfs].usReportSize;
    pIntData = (BYTE *)&gJOY[joyIndex].buffer;

    // No proper index or Value to long
    if( (FULL_WORD==usOffset) || (usSize>32) )
        return rc;

    StartBit = usOffset %8;
    usByteOfs = usOffset /8;

    //Check if in bounds of report
    if(usByteOfs>=gJOY[joyIndex].ReportLength)
        return rc;

    if(usSize>1)
    {
        if(!StartBit){
            // probably the easiest
            while(usSize>=8){
                rc *= 256;
                rc += pIntData[usByteOfs++];
                usSize-=8;
            }
            if(usSize){
                rc *= (2*usSize);
                bRem = pIntData[usByteOfs];
                bRem >>=(8-usSize);
                rc += bRem;
            }
        }
    }
    ...
}
```

GetLogValue cont.

```
... else{
    if( (StartBit-usSize)<=0){
        // All bits are in this byte
        bRem = pIntData[usByteOfs];
        bRem &= gRightMask[StartBit];
        bRem >>= (8-usSize-StartBit);
        rc = bRem;
    }
    else
    {
        bRem = pIntData[usByteOfs++];
        bRem &=gRightMask[StartBit];
        rc = bRem;
        usSize -= (8-StartBit);
        while(usSize>=8){
            rc *= 256;
            rc += pIntData[usByteOfs++];
            usSize-=8;
        }
        if(usSize){
            rc *= (2*usSize);
            bRem = pIntData[usByteOfs];
            bRem >>=(8-usSize);
            rc += bRem;
        }
    }
}
else // 1 Byte only
{
    bRem = pIntData[usByteOfs] & gBitMask[StartBit];
    bRem >>= (7-StartBit);
    rc = bRem;
}
return rc;
}
```

Useful information links

General info docs etc www.usb.org

USB device information www.linux-usb.org

Sources for many linux USB drivers
www.sourceforge.net

The OS/2 DDK with sources of USB drivers
service.boulder.ibm.com/ddk/